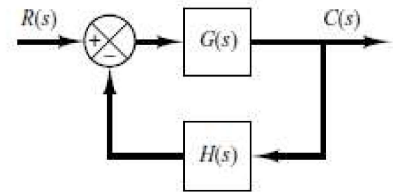


Root Locus Method

Angle and Magnitude Conditions

- Consider the negative feedback system below, the closed-loop transfer function is

$$\frac{C(s)}{R(s)} = \frac{G(s)}{1 + G(s)H(s)}$$



- The **characteristic equation** is obtained by setting the denominator of the above function equal to zero:

$$\Delta(s) = 1 + G(s)H(s) = 0 \quad \text{or} \quad G(s)H(s) = -1$$

- The values of s that fulfill both the **angle and magnitude conditions** are the roots of the characteristic equation, or the closed-loop poles,

Angle Condition: $\angle G(s)H(s) = \pm 180^\circ(2k + 1), \quad k = 0, 1, 2, \dots$

Magnitude Condition: $|G(s)H(s)| = 1$

1

Root Locus Method

Angle and Magnitude Conditions

- A locus of the points in the complex plane satisfying the **angle condition alone** is the **root locus**
- The roots of the characteristic equation (the closed-loop poles) corresponding to a given value of the **gain** can be determined from the **magnitude condition**
- In many cases, $G(s)H(s)$ involves a **gain parameter** K , and the characteristic equation may be written as,

$$1 + \frac{K(s + z_1)(s + z_2) \cdots (s + z_m)}{(s + p_1)(s + p_2) \cdots (s + p_n)} = 0$$

- The root loci for the system are the loci of the closed-loop poles as the **gain** K is varied from **zero to infinity**
- The root loci are always **symmetrical** about the real axis
- Remember that the **angles** of the complex quantities originating from the open-loop poles and open-loop zeros to the test point s are measured in the **counterclockwise direction**

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Root Locus Method

Angle and Magnitude Conditions

- For example, if $G(s)H(s)$ is given by,

$$G(s)H(s) = \frac{K(s + z_1)}{(s + p_1)(s + p_2)(s + p_3)(s + p_4)}$$

(how about the root nature of the above equation?)

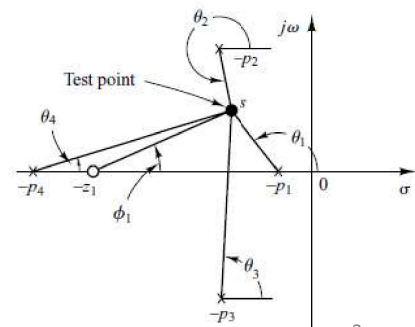
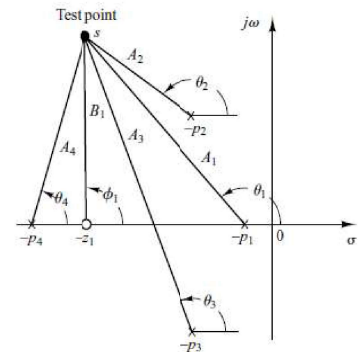
- The angle of $G(s)H(s)$ is then,

$$\angle G(s)H(s) = \phi_1 - \theta_1 - \theta_2 - \theta_3 - \theta_4$$

- The magnitude of $G(s)H(s)$ for this system is

$$|G(s)H(s)| = \frac{KB_1}{A_1A_2A_3A_4}$$

where A_1, A_2, A_3, A_4 , and B_1 are the magnitudes of the complex quantities $s + p_1, s + p_2, s + p_3, s + p_4$, and $s + z_1$, respectively



3

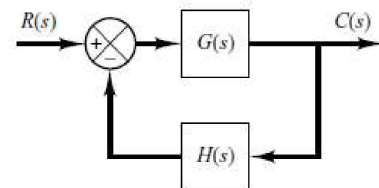
General Rules for Constructing Root Loci

- First, obtain the characteristic equation

$$1 + G(s)H(s) = 0$$

- Then rearrange this equation in the form of

$$1 + \frac{K(s + z_1)(s + z_2) \cdots (s + z_m)}{(s + p_1)(s + p_2) \cdots (s + p_n)} = 0 \quad \text{For } K > 0$$



1. Locate the poles and zeros of $G(s)H(s)$ on the s plane

The root-locus branches start from **open-loop** poles and terminate at zeros (finite zeros or zeros at infinity), as K increases from zero to infinity

Number of branches are equal to the number of roots of the characteristic equation

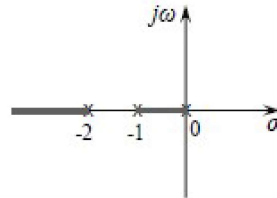
4

General Rules for Constructing Root Loci

2. Determine the root loci on the real axis

If the total number of **real** poles and **real** zeros to the right of this test point is odd, then this point lies on a root locus

Example:



- Select a **test point**, s , in each interval
- If select a test point on the negative real axis **between 0 and -1**,

$$\angle s = 180^\circ, \quad \angle(s+1) = \angle(s+2) = 0^\circ$$

$$\therefore -\angle s - \angle(s+1) - \angle(s+2) = \pm 180^\circ(2k+1), k = 0, 1, 2, 3 \dots$$

- **satisfies angle condition and this range forms a portion of the root locus**

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General Rules for Constructing Root Loci

3. Determine the asymptotes of root loci

The root loci for very large values of s must be asymptotic to straight lines whose angles (slopes) are given by

$$\text{Angles of asymptotes} = \frac{\pm 180^\circ(2k+1)}{n-m} \quad (k = 0, 1, 2, \dots)$$

where n = no. of finite **poles** of $G(s)H(s)$ and m = no. of finite **zeros** of $G(s)H(s)$

All the asymptotes intersect at a point on the real axis. The point at which they do so is obtained by

$$s = \frac{\sum \text{poles} - \sum \text{zeros}}{n-m}$$

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General Rules for Constructing Root Loci

4. Find the breakaway and break-in points

If a root locus lies between two adjacent open-loop poles on the real axis, then there

exists **at least one breakaway point between the two poles**

If the root locus lies between two adjacent zeros on the real axis, then there always exists **at least one break-in point between the two zeros**

Suppose that the **characteristic equation** is given by $B(s) + KA(s) = 0$

The breakaway and break-in points can be determined from the roots of

$$\frac{dK}{ds} = -\frac{B'(s)A(s) - B(s)A'(s)}{A^2(s)}$$

If a real root is **NOT on the root locus portion** of the real axis, this root is **NOT** the actual breakaway or break-in point

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General Rules for Constructing Root Loci

5. Determine the angle of departure (angle of arrival) of the root locus from a **complex pole** (at a **complex zero**)

Angle of departure from a complex pole = 180°

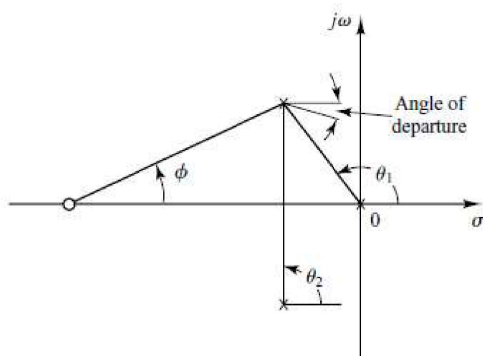
– (sum of the angles of vectors to a complex pole in question from other poles)

+ (sum of the angles of vectors to a complex pole in question from zeros)

Angle of arrival at a complex zero = 180°

– (sum of the angles of vectors to a complex zero in question from other zeros)

+ (sum of the angles of vectors to a complex zero in question from poles)



Angle of departure = ?

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General Rules for Constructing Root Loci

6. Find the points where the root loci may cross the imaginary axis

- (a) Use of Routh's stability criterion; OR
- (b) Put $s = j\omega$ in the **characteristic equation**, equating both the real part and the imaginary part to zero, and solving for ω and K

7. Determine the closed-loop poles or Draw the root locus

A particular point on each root-locus branch will be a **closed-loop pole** if the value of K at that point satisfies the **magnitude condition**, $|G(s)H(s)| = 1$

The value of K corresponding to any point s on a root locus can be obtained using the magnitude condition, or

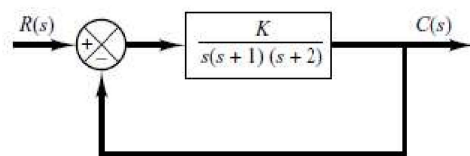
$$K = \frac{\text{product of lengths between point } s \text{ to poles}}{\text{product of lengths between point } s \text{ to zeros}}$$

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Example 6

Consider the negative feedback system shown below. For this system,

$$G(s) = \frac{K}{s(s+1)(s+2)}, \quad H(s) = 1$$

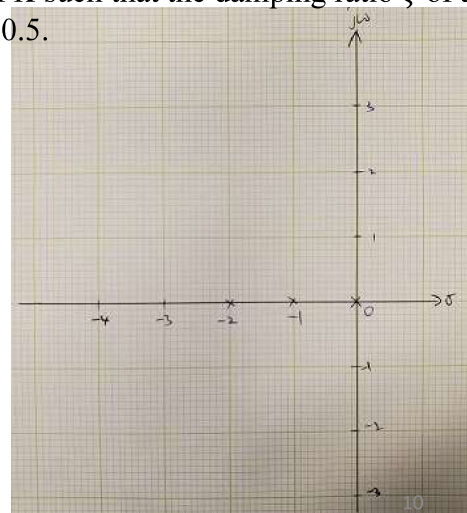


Sketch the root-locus plot and then determine the value of K such that the damping ratio ζ of a pair of dominant complex-conjugate closed-loop poles is 0.5.

Answer:

1. Locate the poles and zeros of $G(s)H(s)$ on the s plane

Pole: $s = 0, s = -1, s = -2$

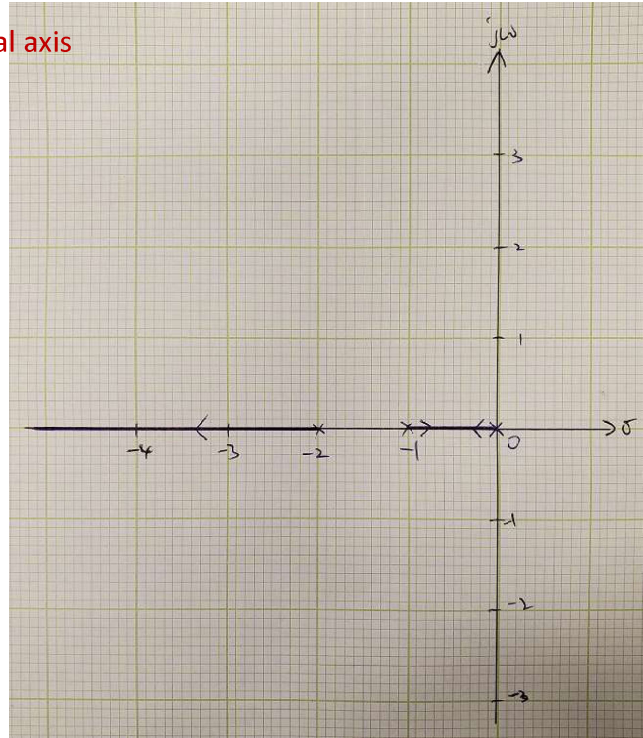


Example 6 (continued)

2. Determine the root loci on the real axis

$$(-1, 0)$$

$$(-\infty, -2)$$



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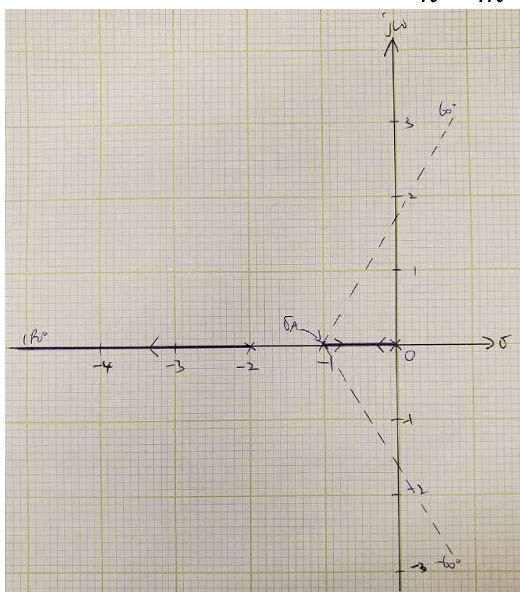
Example 6 (continued)

3. Determine the asymptotes of root loci

$$\text{Angles of asymptotes} = \frac{\pm 180^\circ(2k + 1)}{n - m} \quad (k = 0, 1, 2, \dots)$$

$$= \frac{\pm 180^\circ(2k + 1)}{3 - 0} = \pm 60^\circ(2k + 1)$$

$$= \pm 60^\circ, \pm 180^\circ$$



$$s = \frac{\sum \text{poles} - \sum \text{zeros}}{n - m}$$

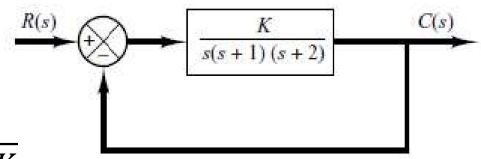
$$s = \frac{(0) + (-1) + (-2)}{3 - 0} = -1$$

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Example 6 (continued)

4. Find the breakaway and break-in points

$$\frac{C(s)}{R(s)} = \frac{\frac{K}{s(s+1)(s+2)}}{1 + \frac{K}{s(s+1)(s+2)}} = \frac{K}{s(s+1)(s+2) + K}$$



$$\therefore \frac{C(s)}{R(s)} = \frac{1}{1 + G(s)H(s)}$$

$$\Delta(s) = s(s+1)(s+2) + K = 0$$

$$\therefore \Delta(s) = 1 + G(s)H(s)$$

$$= s^3 + 3s^2 + 2s + K = 0$$

$$\therefore K = -s^3 - 3s^2 - 2s$$

Rejected and why?

$$\frac{dK}{ds} = -3s^2 - 6s - 2 = 0$$

$$s = -0.423, -1.58$$

Only breakaway point

$$K = -(-0.423)^3 - 3(-0.423)^2 - 2(-0.423) = 0.385$$

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Example 6 (continued)

5. Determine the angle of departure (angle of arrival) of the root locus from a complex pole (at a complex zero)

Since there are neither **complex pole(s)** nor **complex zero(s)**, this step can be omitted

Example 6 (continued)

6. Find the points where the root loci may cross the imaginary axis

The characteristic equation, $\Delta(s) = s^3 + 3s^2 + 2s + K = 0$

Routh Array
Method

Using Routh array,

$$\begin{array}{l} s^3 \\ s^2 \\ s^1 \\ s^0 \end{array} \left| \begin{array}{cc} 1 & 2 \\ 3 & K \\ \hline 6-K & \\ 3 & \\ K & \end{array} \right.$$

For stability: $0 < K < 6$

The crossing points on the imaginary axis can then be found by solving the auxiliary equation obtained from the s^2 row; that is,

$$3s^2 + K = 3s^2 + 6 = 0 \Rightarrow s = \pm j\sqrt{2}$$

The frequencies at the crossing points on the imaginary axis are thus $\omega = \pm\sqrt{2}$.
The gain value corresponding to the crossing points is $K = 6$.

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Example 6 (continued)

6. Find the points where the root loci may cross the imaginary axis

Put $s = j\omega$ into $\Delta(s)$,

Equating
term Method

$$\Delta(j\omega) = (j\omega)^3 + 3(j\omega)^2 + 2(j\omega) + K = 0$$

$$= -j\omega^3 - 3\omega^2 + 2j\omega + K = 0$$

Equating terms, we have

$$-j\omega^3 + 2j\omega = 0$$

$$-3\omega^2 + K = 0$$

$$-j\omega(\omega^2 - 2) = 0$$

$$3(\sqrt{2})^2 = K$$

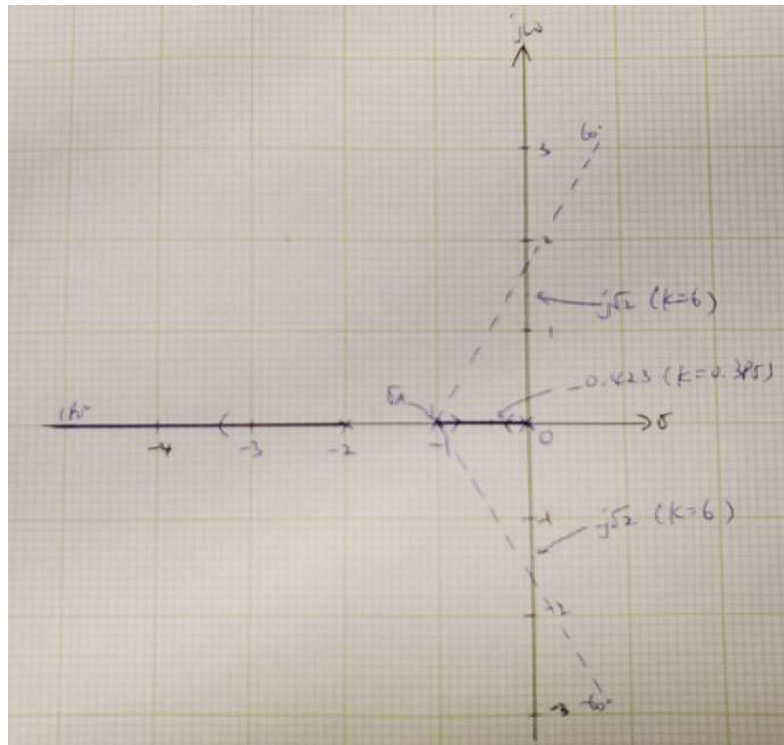
$$\therefore \omega = 0, \pm\sqrt{2}$$

$$\therefore K = 6$$

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Example 6 (continued)

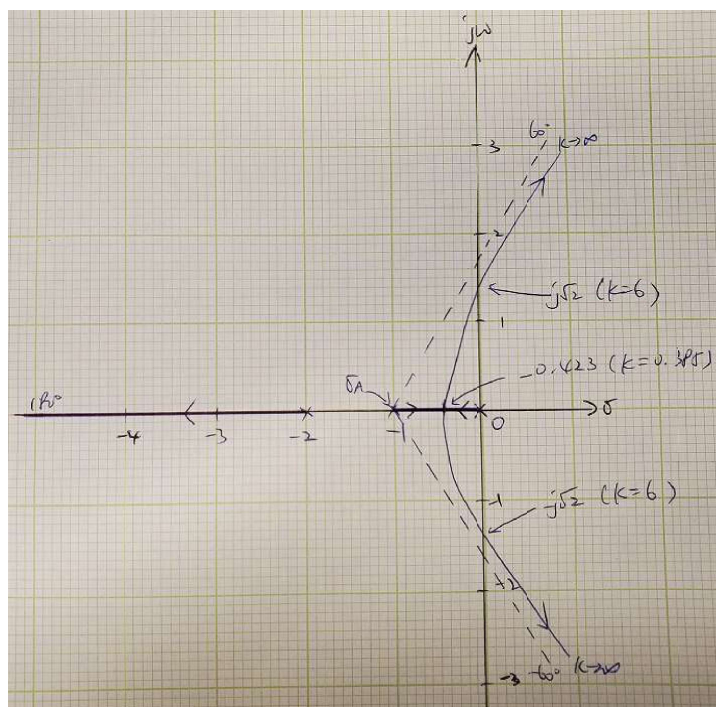
6. Find the points where the root loci may cross the imaginary axis



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Example 6 (continued)

7. Determine the closed-loop poles or Draw the root locus



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