

SEHS4653 Control System Analysis Tutorial Questions (Part 3) Solution

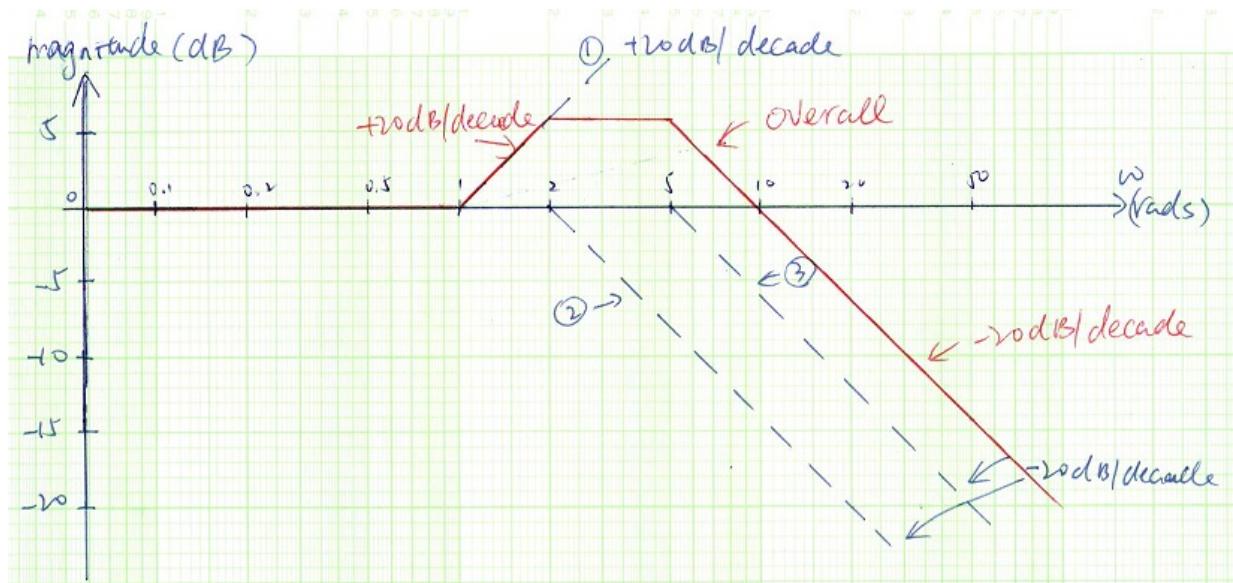
$$1. \text{ (a)} \quad G(s) = \frac{10(s+1)}{(s+2)(s+5)}$$

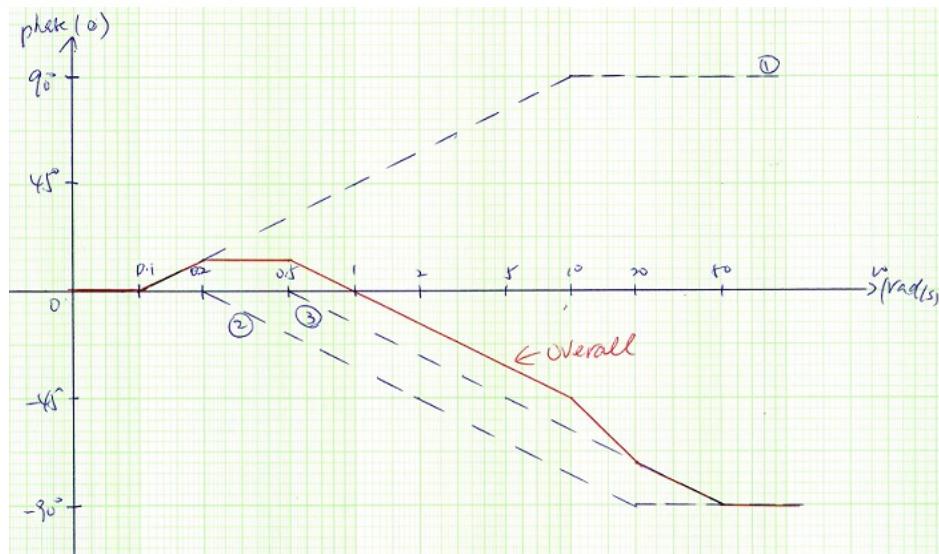
Asymptotic Bode Diagram:

$$G(j\omega) = \frac{10(j\omega + 1)}{(j\omega + 2)(j\omega + 5)} = \frac{10(j\omega + 1)}{\left(1 + \frac{j\omega}{2}\right)\left(2\right)\left(1 + \frac{j\omega}{5}\right)\left(5\right)} = \frac{j\omega + 1}{\left(1 + \frac{j\omega}{2}\right)\left(1 + \frac{j\omega}{5}\right)}$$

From the standard form, we have identified 3 basic factors:

1. Zero: $j\omega + 1$; Corner frequency: $\omega = 1 \text{ rad/s}$
2. Pole: $1 + \frac{j\omega}{2}$; Corner frequency: $\omega = 2 \text{ rad/s}$
3. Pole: $1 + \frac{j\omega}{5}$; Corner frequency: $\omega = 5 \text{ rad/s}$





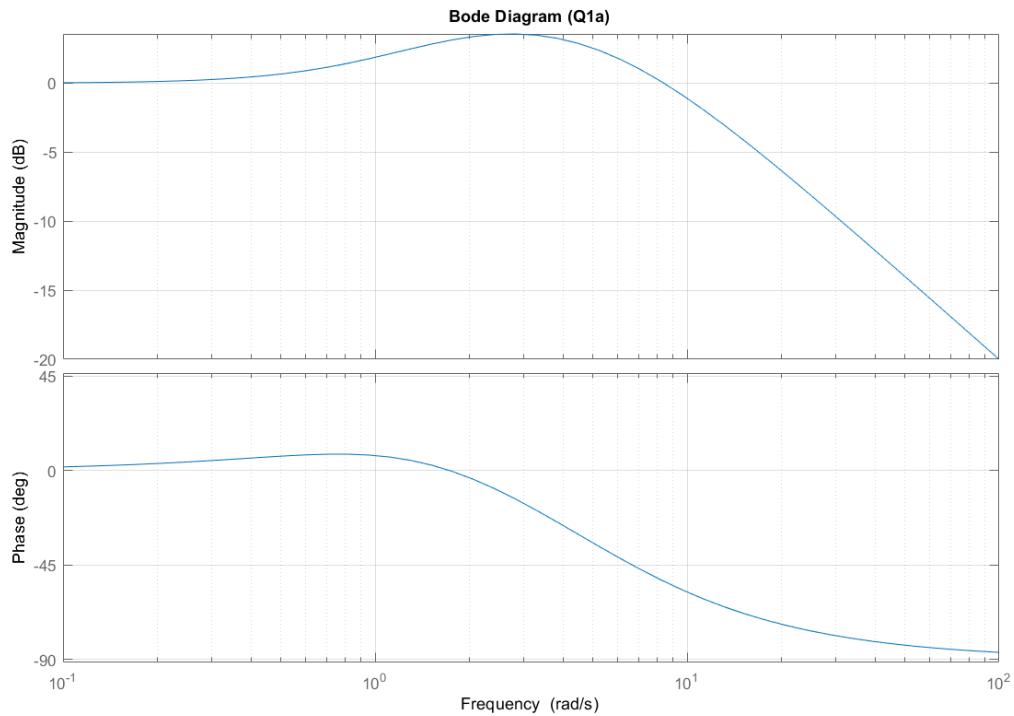
Exact Bode Diagram:

$$G(j\omega) = \frac{10(j\omega + 1)}{(j\omega + 2)(j\omega + 5)}$$

$$|G(j\omega)| = 20 \log \frac{10\sqrt{1^2 + \omega^2}}{\sqrt{2^2 + \omega^2}\sqrt{5^2 + \omega^2}} \text{ (dB)}$$

$$\angle G(j\omega) = \tan^{-1} \omega - \tan^{-1} \frac{\omega}{2} - \tan^{-1} \frac{\omega}{5} \text{ } (\circ)$$

ω (rad/s)	Magnitude (dB)	Phase (°)
0.1	0.0306	1.702
0.5	0.663	6.818
1	1.871	7.125
2	3.335	-3.366
5	2.536	-34.508
8	0.310	-51.083
10	-1.096	-57.836
15	-4.037	-67.784
20	-6.316	-73.116
30	-9.676	-78.633
50	-14.028	-83.145
80	-20.012	-85.708



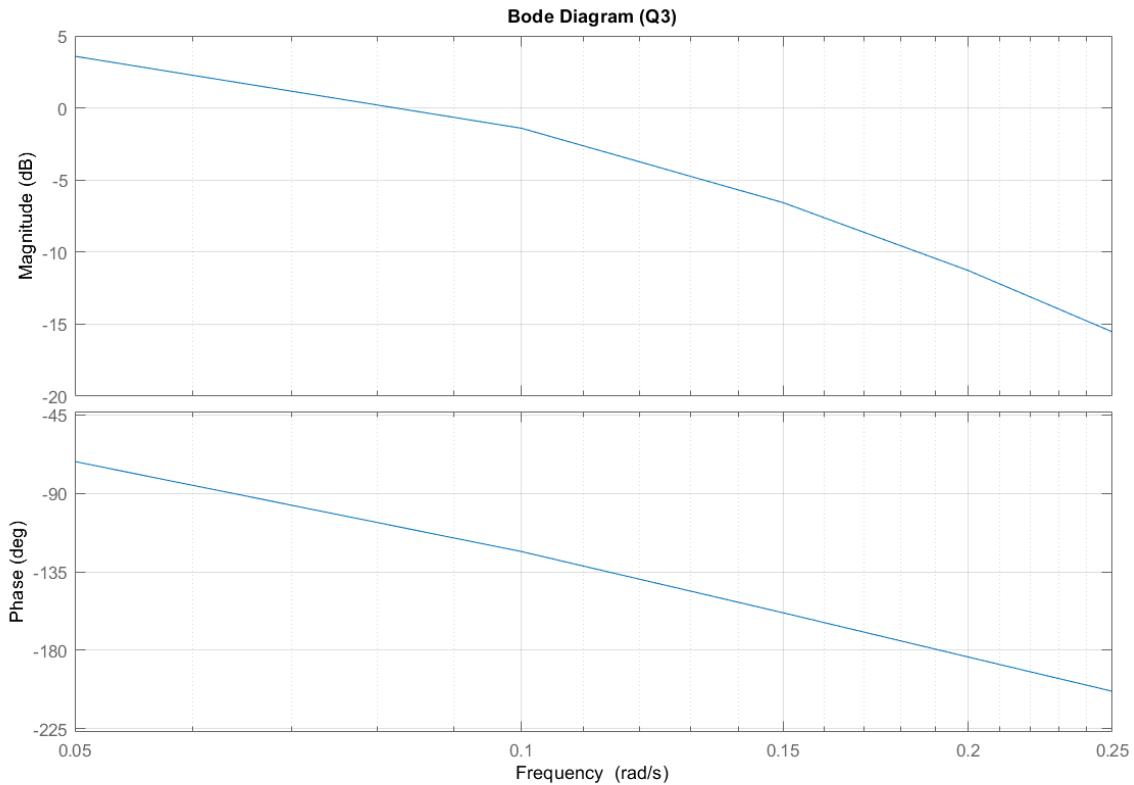
$$2. \quad G(s) = \frac{2}{(1+2s)(1+3s)(1+11s)^2}$$

$$G(j\omega) = \frac{2}{(1+2j\omega)(1+3j\omega)(1+11j\omega)^2}$$

$$|G(j\omega)| = 20 \log \frac{2}{\sqrt{1^2 + (2\omega)^2} \sqrt{1^2 + (3\omega)^2} \left(\sqrt{1^2 + (11\omega)^2}\right)^2} \quad (\text{dB})$$

$$\angle G(j\omega) = -\tan^{-1} 2\omega - \tan^{-1} 3\omega - \tan^{-1} 11\omega - \tan^{-1} 11\omega \quad (\text{°})$$

ω (rad/s)	Magnitude (dB)	Phase (°)
0.05	3.585	-71.86
0.1	-1.412	-123.46
0.15	-6.571	-158.49
0.2	-11.288	-183.88
0.25	-15.539	-203.47



3. (a)

$$G(s) = \frac{K}{s(s+2)(s+10)}$$

$$G(j\omega) = \frac{K}{j\omega(j\omega+2)(j\omega+10)}$$

$$|G(j\omega)| = 20 \log \frac{K}{\omega \sqrt{\omega^2 + 2^2} \sqrt{\omega^2 + 10^2}} \quad (\text{dB})$$

$$\angle G(j\omega) = -90^\circ - \tan^{-1} \frac{\omega}{2} - \tan^{-1} \frac{\omega}{10} \quad (\text{deg})$$

When system phase $\phi = -180^\circ$, and put into the phase equation, we can find the phase crossover frequency, ω_{pc} :

$$-180^\circ = -90^\circ - \tan^{-1} \frac{\omega}{2} - \tan^{-1} \frac{\omega}{10} \quad \Rightarrow \quad \tan^{-1} \frac{\omega}{2} + \tan^{-1} \frac{\omega}{10} = 90^\circ$$

$$\frac{\frac{\omega}{2} + \frac{\omega}{10}}{1 - \frac{\omega^2}{20}} = \infty \quad \Rightarrow \quad 1 - \frac{\omega^2}{20} = 0$$

$$\therefore \omega = \sqrt{20} \text{ rad/s or } 4.47 \text{ rad/s}$$

Substitute into this phase crossover frequency into the magnitude equation, we have

$$|G(j\omega)| = 20 \log \frac{K}{\sqrt{20} \sqrt{(\sqrt{20})^2 + 2^2} \sqrt{(\sqrt{20})^2 + 10^2}} = 20 \log \frac{K}{\sqrt{20} \sqrt{24} \sqrt{120}}$$

If gain margin = 6 dB, we have

$$20 \log \frac{K}{\sqrt{20} \sqrt{24} \sqrt{120}} = -6$$

$$\therefore K = 120.28$$

3. (b) With the phase margin = 45°, the corresponding open-loop phase = -135°

$$-135^\circ = -90^\circ - \tan^{-1} \frac{\omega}{2} - \tan^{-1} \frac{\omega}{10} \Rightarrow \tan^{-1} \frac{\omega}{2} + \tan^{-1} \frac{\omega}{10} = 45^\circ$$

$$\frac{\frac{\omega}{2} + \frac{\omega}{10}}{1 - \frac{\omega^2}{20}} = 1 \Rightarrow 1 - \frac{\omega^2}{20} = \frac{\omega}{2} + \frac{\omega}{10} \Rightarrow \frac{\omega^2}{20} + \frac{6\omega}{10} - 1 = 0 \Rightarrow \frac{\omega^2 + 12\omega - 20}{20} = 0$$

$$\therefore \omega = 1.48 \text{ rad/s or } -13.48 \text{ rad/s (rejetced)}$$

Noting that the magnitude of the system ($|G(j\omega)|$) must be equal to 0 dB at $\omega = 1.48$ rad/s, we have

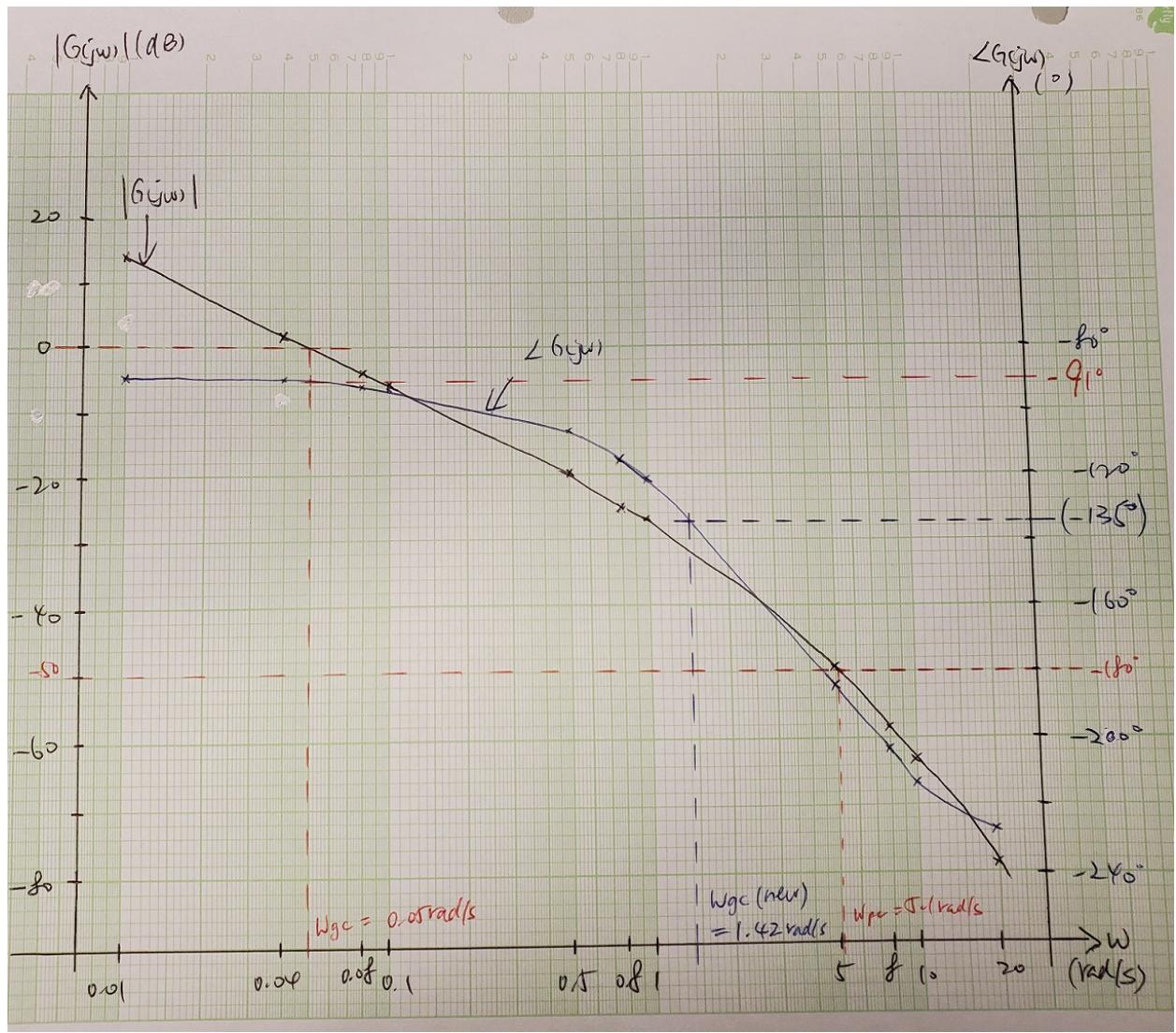
$$|G(j\omega)| = 20 \log \frac{K}{1.48 \sqrt{(1.48)^2 + 2^2} \sqrt{(1.48)^2 + 10^2}} = 0$$

$$\therefore K = 37.22$$

3. (c) From the system magnitude and phase equations obtained in part (a), we can draw the exact Bode diagrams

ω (rad/s)	$ G(j\omega) $ (dB)	$\angle G(j\omega)$ (°)
0.01	14.0	-90.3
0.04	1.9	-91.4
0.08	-4.1	-92.7
0.1	-6.0	-93.4
0.5	-20.2	-106.9
0.8	-24.8	-116.4
1	-27.0	-122.3
5	-49.6	-184.8
8	-58.5	-204.6

10	-63.2	-213.7
20	-79.1	-237.7



From the exact bode diagrams, the gain margin = 50 dB (G.M. = $0 - |G(j\omega)|$) at 5.1 rad/s. Phase margin = 89° at 0.05 rad/s.

$$\text{G.M.} = 6 = 0 - |G(j\omega)| \quad (\text{phase crossover frequency will not change})$$

$$\therefore |G(j\omega)| = 20 \log \frac{K}{5.1\sqrt{(5.1)^2 + 2^2}\sqrt{(5.1)^2 + 10^2}} = -6$$

$$\therefore K = 157.18$$

$$\text{P.M.} = 180^\circ + \angle G(j\omega) = 45^\circ, \angle G(j\omega) = -135^\circ$$

From the exact bode diagrams, the gain crossover frequency at $\angle G(j\omega) = -135^\circ$ is 1.42 rad/s

$$\therefore |G(j\omega)| = 20 \log \frac{K}{1.42\sqrt{(1.42)^2 + 2^2}\sqrt{(1.42)^2 + 10^2}} = 0$$

$$\therefore K = 35.18$$

4. From the block diagram, the open-loop transfer function is,

$$G(s) = \frac{K}{s(s+1)(s+5)}$$

Plot the exact Bode diagrams for finding gain margin and phase margin with $K = 10$ and $K = 100$.

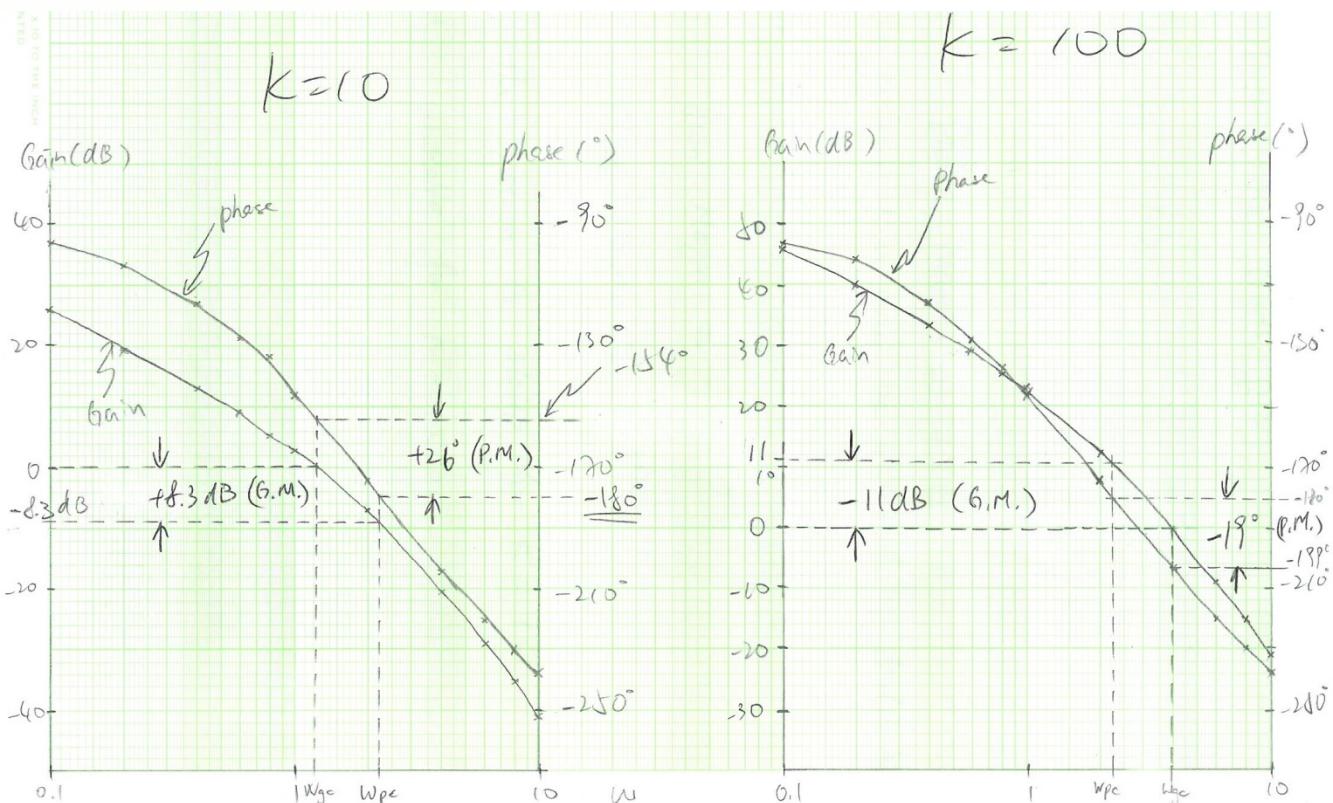
$$G(j\omega) = \frac{K}{j\omega(j\omega+1)(j\omega+5)}$$

$$|G(j\omega)| = 20 \log \frac{K}{\omega\sqrt{\omega^2 + 1^2}\sqrt{\omega^2 + 5^2}} \text{ (dB)}$$

$$\angle G(j\omega) = -90^\circ - \tan^{-1} \omega - \tan^{-1} \frac{\omega}{5} \text{ (°)}$$

Change of gain K will Not alter the system phase, we have

ω (rad/s)	Magnitude (dB)		Phase (°)
	$K = 10$	$K = 100$	
0.1	25.98	45.98	-96.86
0.2	19.82	39.82	-103.13
0.4	13.31	33.31	-116.38
0.6	9.06	29.06	-127.81
0.8	5.70	25.70	-137.75
1	2.84	22.84	-146.31
2	-7.63	12.37	-175.24
4	-20.47	-0.47	-204.62
6	-29.10	-9.1	-220.73
8	-35.68	-15.68	-230.87
10	-41.01	-21.01	-237.72



K	Gain margin	Phase margin
10	+8.3 dB	+26°
100	-11 dB	-19°

Hence, the system is stable for $K = 10$, but unstable for $K = 100$.

5. From the block diagram, the open-loop transfer function, we have

$$G(s) = \frac{K(s+2)}{s^2}$$

$$G(j\omega) = \frac{K(j\omega + 2)}{(j\omega)^2}$$

$$|G(j\omega)| = 20 \log \frac{K\sqrt{\omega^2 + 2^2}}{\omega^2} \text{ (dB)}$$

$$\angle G(j\omega) = \tan^{-1} \frac{\omega}{2} - 90^\circ - 90^\circ \text{ (°)}$$

The required phase margin of 50° means that the system phase be equal to -130° . Hence, the gain crossover frequency can be found from the system phase equation as follow,

$$-130^\circ = \tan^{-1} \frac{\omega}{2} - 90^\circ - 90^\circ \Rightarrow \tan^{-1} \frac{\omega}{2} = 50^\circ$$

$$\therefore \omega_{gc} = 2.3835 \text{ rad/s}$$

Noting that the magnitude of the system ($|G(j\omega)|$) must be equal to 0 dB at $\omega = 2.3835 \text{ rad/s}$, we have

$$20 \log \frac{K\sqrt{2.3835^2 + 2^2}}{2.3835^2} = 0$$

$$\therefore K = 1.826$$

End of Tutorial Questions (Part 3) Solution