

SEHS4653 Control System Analysis Tutorial Questions (Part 1)

Laplace Transform

1. Solve the following differential equations using Laplace transform method.

(a) $\dot{y}(t) + y(t) = 2e^t$, $y(0) = 4$ Ans: $y(t) = e^t + 3e^{-t}$

(b) $\ddot{y}(t) + 3\dot{y}(t) + 2y(t) = 1$, $y(0) = -1$, $\dot{y}(0) = 0$ Ans: $y(t) = \frac{1}{2} - 3e^{-t} + \frac{3}{2}e^{-2t}$

2. Find the unit-step and unit-impulse response of the following systems in time domain.

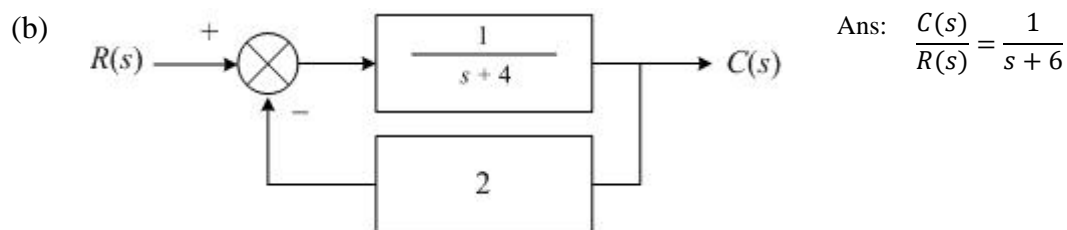
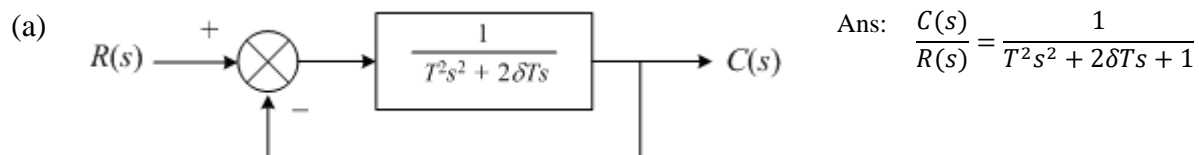
(a) $\ddot{y}(t) + 2\dot{y}(t) + y(t) = r(t)$ Ans: $u(t) = 1 - te^{-t} - e^{-t}$, $h(t) = te^{-t}$

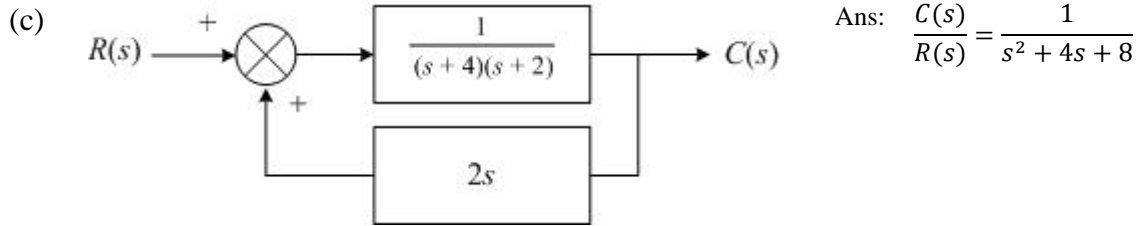
(b) $\dot{y}(t) + y(t) = r(t)$ Ans: $u(t) = t - 1 + e^{-t}$, $h(t) = 1 - e^{-t}$

(c) $\ddot{y}(t) + 2\dot{y}(t) + 2y(t) = r(t)$ Ans: $u(t) = \frac{1}{2} - \frac{1}{2}e^{-t} \cos t - \frac{1}{2}e^{-t} \sin t$, $h(t) = e^{-t} \sin t$

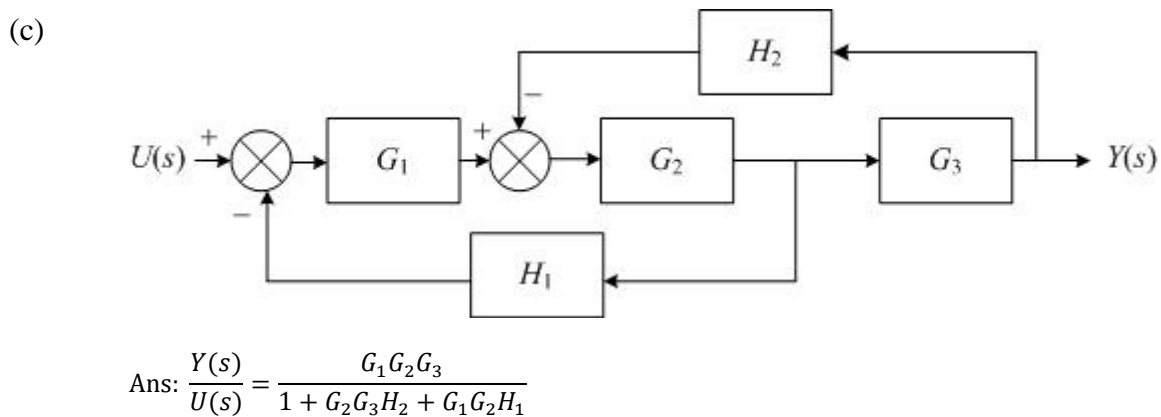
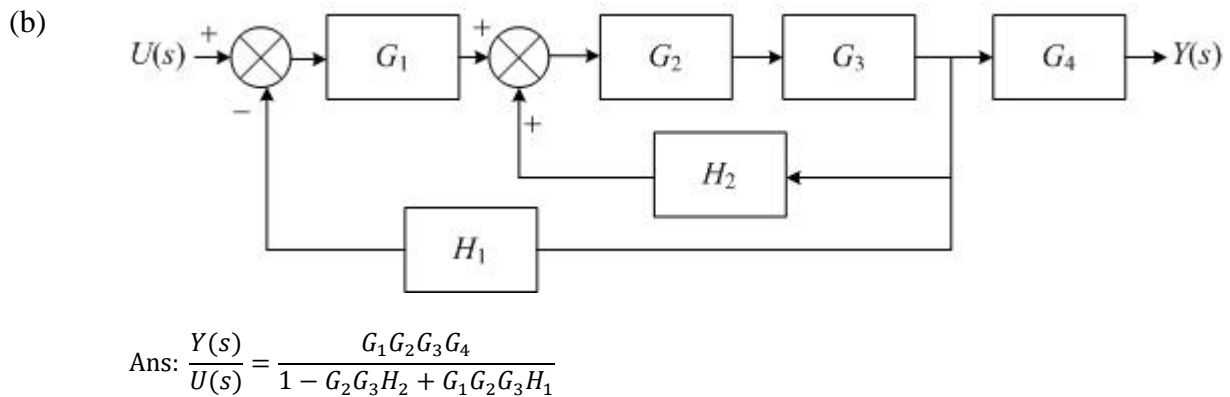
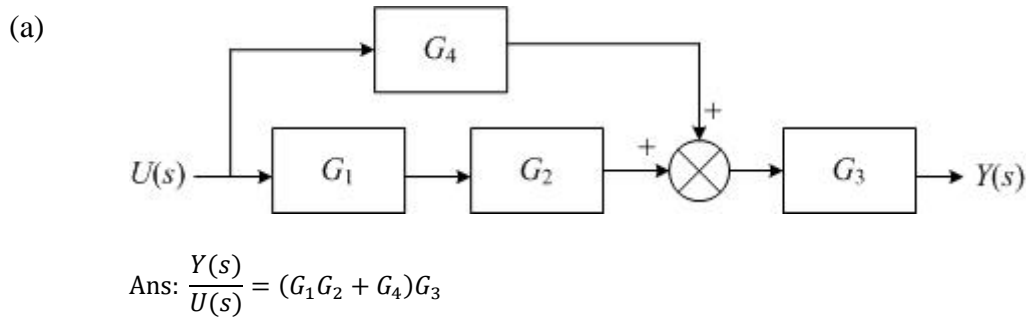
Block Diagrams

3. Find the closed-loop transfer function for the systems shown below.

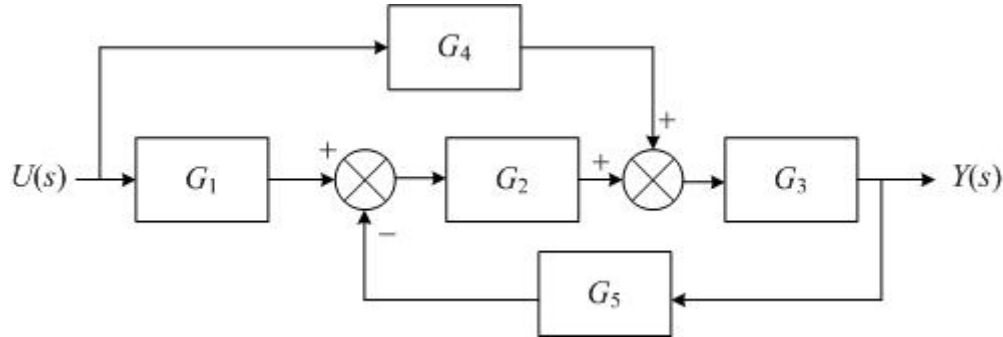




4. Reduce the block diagrams shown below to obtain the transfer function using block combination rules.



(d)



$$\text{Ans: } \frac{Y(s)}{U(s)} = \frac{G_3(G_1G_2 + G_4)}{1 + G_2G_3G_5}$$

Signal Flow Graphs

5. Construct the signal flow graph for the following set of simultaneous equations.

$$x_2 = A_{12}x_1 + A_{32}x_3$$

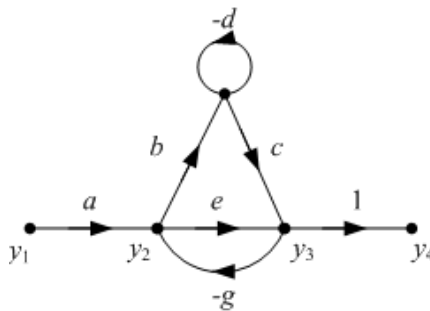
$$x_3 = A_{13}x_1 + A_{23}x_2 + A_{33}x_3$$

$$x_4 = A_{24}x_2 + A_{34}x_3$$

Hence determine the transfer function (x_4/x_1) using the Mason's rule.

$$\text{Ans: } \frac{x_4}{x_1} = \frac{A_{21}A_{42}(1 - A_{33}) + A_{23}A_{31}A_{42} + A_{31}A_{43} + A_{21}A_{32}A_{43}}{1 - A_{23}A_{32} - A_{33}}$$

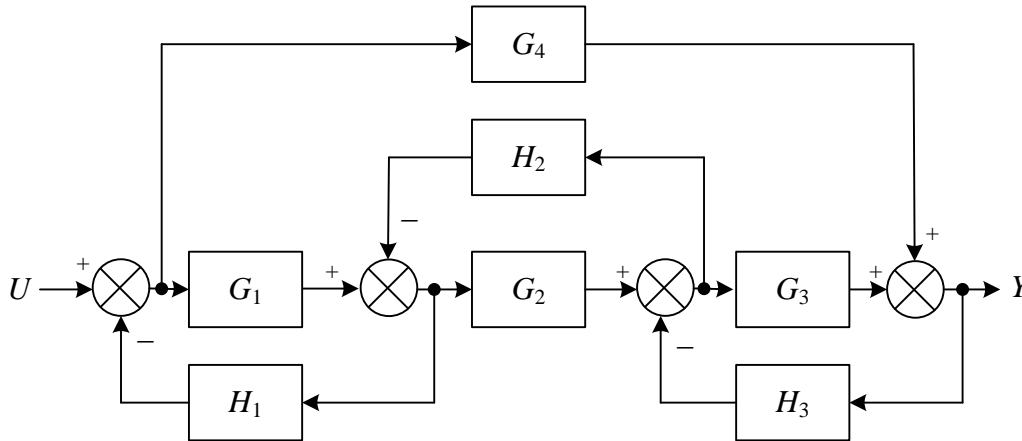
6. Consider the signal flow graph below:



Hence determine the transfer function (y_4/y_1) using the Mason's rule.

$$\text{Ans: } \frac{y_4}{y_1} = \frac{ae(1 + d) + abc}{1 + d + eg + bcg + edg}$$

7. Construct a signal flow graph for the below block diagram and hence determine its transfer function by using Mason's rule.



Ans:
$$\frac{Y(s)}{U(s)} = \frac{G_1 G_2 G_3 + G_4 + G_2 G_4 H_2}{1 + G_1 H_1 + G_2 H_2 + G_3 H_3 + G_4 H_1 H_2 H_3 + G_1 G_3 H_1 H_3}$$

System Modelling

8. A very simplified version of the suspension system is shown in Figure 1 below. Assuming that the motion x_i at point P is the input to the system and the vertical motion x_o of the body is the output, obtain the transfer function $X_o(s)/X_i(s)$. (Consider the motion of the body only in the vertical direction.) Displacement x_o is measured from the equilibrium position in the absence of input x_i .

Ans:
$$\frac{X_o(s)}{X_i(s)} = \frac{bs + k}{ms^2 + bs + k}$$

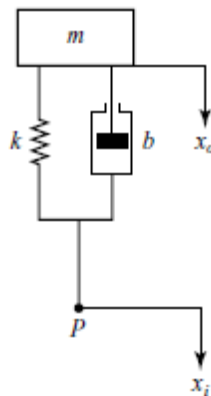


Figure 1

9. Obtain the transfer function $E_o(s)/E_i(s)$ of the electrical systems shown in Figures 3 and 4 below **using impedance method**.

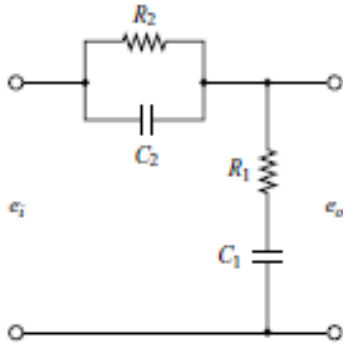


Figure 3

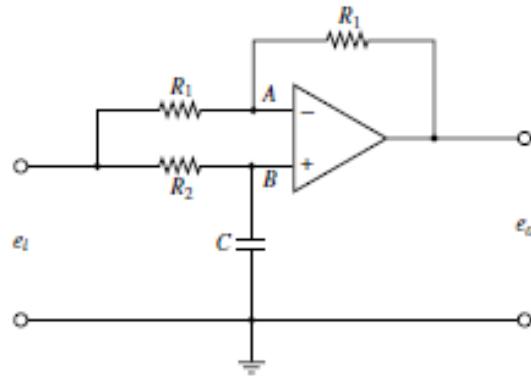


Figure 4

Ans:
$$\frac{E_o(s)}{E_i(s)} = \frac{(sR_1C_1 + 1)(sR_2C_2 + 1)}{sR_2C_1 + (sR_1C_1 + 1)(sR_2C_2 + 1)}$$

Ans:
$$\frac{E_o(s)}{E_i(s)} = \frac{1 - sR_2C}{sR_2C + 1}$$

End of Tutorial Questions (Part 1)