

SEHS4653 Control System Analysis

Laplace Transform Table

updated on 10 Jan 2023

	Time Function $f(t)$	Laplace Transform $F(s)$
1	Unit-impulse function $\delta(t)$	1
2	Unit-step function $u_s(t)$	$\frac{1}{s}$
3	Unit-ramp function t	$\frac{1}{s^2}$
4	t^n ($n = \text{positive integer}$)	$\frac{n!}{s^{n+1}}$
5	e^{-at}	$\frac{1}{s + a}$
6	te^{-at}	$\frac{1}{(s + a)^2}$
7	$t^n e^{-at}$ ($n = \text{positive integer}$)	$\frac{n!}{(s + a)^{n+1}}$
8	$\sin \omega t$	$\frac{\omega}{s^2 + \omega^2}$
9	$\cos \omega t$	$\frac{s}{s^2 + \omega^2}$
10	$\frac{1}{a}(1 - e^{-at})$	$\frac{1}{s(s + a)}$
11	$\frac{1}{b-a}(e^{-at} - e^{-bt})$ ($a \neq b$)	$\frac{1}{(s + a)(s + b)}$
12	$\frac{1}{b-a}(be^{-bt} - ae^{-at})$ ($a \neq b$)	$\frac{s}{(s + a)(s + b)}$
13	$\frac{1}{a^2}(1 - e^{-at} - ate^{-at})$	$\frac{1}{s(s + a)^2}$
14	$\frac{1}{a^2}(at - 1 + e^{-at})$	$\frac{1}{s^2(s + a)}$
15	$e^{-at} \sin \omega t$	$\frac{\omega}{(s + a)^2 + \omega^2}$
16	$e^{-at} \cos \omega t$	$\frac{s + a}{(s + a)^2 + \omega^2}$

17	$\frac{\omega_n}{\sqrt{1-\zeta^2}} e^{-\zeta \omega_n t} \sin \omega_n \sqrt{1-\zeta^2} t$	$\frac{\omega_n^2}{s^2 + 2\zeta \omega_n s + \omega_n^2}$
18	$-\frac{1}{\sqrt{1-\zeta^2}} e^{-\zeta \omega_n t} \sin(\omega_n \sqrt{1-\zeta^2} t - \phi)$ where $\phi = \cos^{-1} \zeta$	$\frac{s}{s^2 + 2\zeta \omega_n s + \omega_n^2}$
19	$1 - \frac{1}{\sqrt{1-\zeta^2}} e^{-\zeta \omega_n t} \sin(\omega_n \sqrt{1-\zeta^2} t + \phi)$ where $\phi = \cos^{-1} \zeta$	$\frac{\omega_n^2}{s(s^2 + 2\zeta \omega_n s + \omega_n^2)}$
20	$1 - \cos \omega t$	$\frac{\omega^2}{s(s^2 + \omega^2)}$
21	$\frac{d}{dt} f(t)$	$sF(s) - f(0)$
22	$\frac{d^2}{dt^2} f(t)$	$s^2 F(s) - sf(0) - f'(0)$
23	$\frac{d^n}{dt^n} f(t)$	$s^n F(s) - s^{n-1} f(0) - s^{n-2} f'(0) \dots - sf^{(n-2)}(0) - f^{(n-1)}(0)$
24	$\int f(t) dt$	$\frac{F(s)}{s} + \frac{1}{s} \left[\int f(t) dt \right]$
25	$f(t-T)$	$e^{-Ts} F(s)$
26	$f(\infty) = \lim_{t \rightarrow \infty} f(t)$	$= \lim_{s \rightarrow 0} sF(s)$
27	$f(0^+) = \lim_{t \rightarrow 0^+} f(t)$	$= \lim_{s \rightarrow \infty} sF(s)$