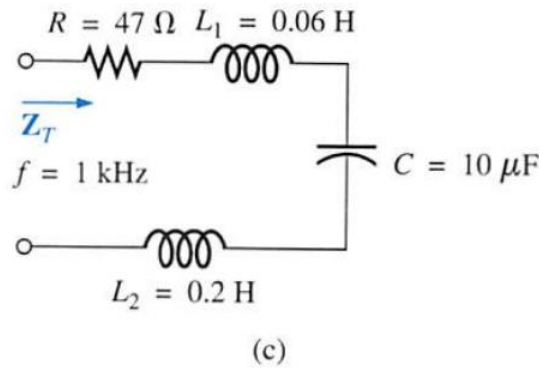


**Tutorial - 1-02-h**

**Question 1 (15-3-5-c)**

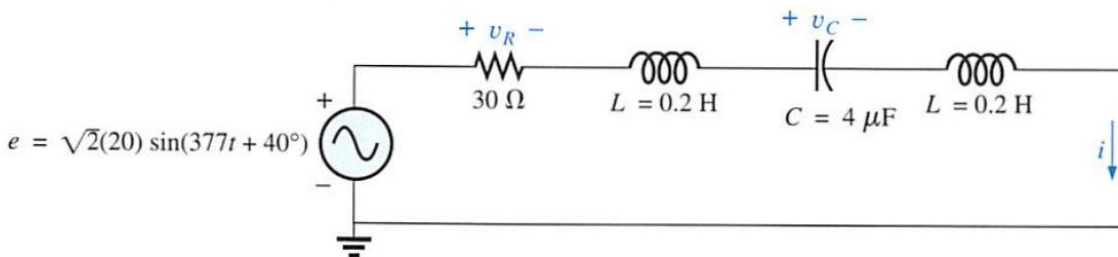
Calculate the total impedance of the circuits of Fig. 15.121. Express your answer in rectangular and polar forms, and draw the impedance diagram.



**Question 2 (15-4-17)**

\*17. For the circuit of Fig. 15.133:

- a. Determine  $\mathbf{I}$ ,  $\mathbf{V}_R$ , and  $\mathbf{V}_C$  in phasor form.
- b. Calculate the total power factor, and indicate whether it is leading or lagging.

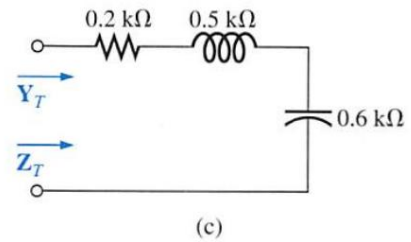
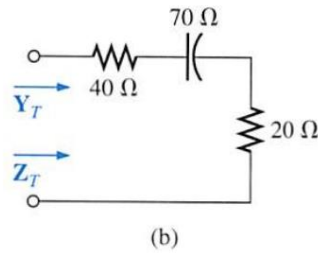
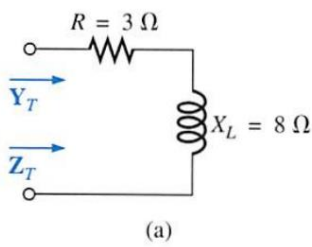


**FIG. 15.133**

- c. Calculate the average power delivered to the circuit.
- d. Draw the impedance diagram.
- e. Draw the phasor diagram of the voltages  $\mathbf{E}$ ,  $\mathbf{V}_R$ , and  $\mathbf{V}_C$ , and the current  $\mathbf{I}$ .
- f. Find the voltages  $\mathbf{V}_R$  and  $\mathbf{V}_C$  using the voltage divider rule, and compare them with the results of part (a) above.
- g. Draw the equivalent series circuit of the above as far as the total impedance and the current  $i$  are concerned.

Question 3 (15-7-25)

25. Find the total admittance and impedance of the circuits of Fig. 15.139. Identify the values of conductance and susceptance, and draw the admittance diagram.



Question 4 (16-2-7)

- \*7. For the network of Fig. 16.42:
- Find the current  $I_1$ .
  - Find the voltage  $V_1$ .
  - Calculate the average power delivered to the network.

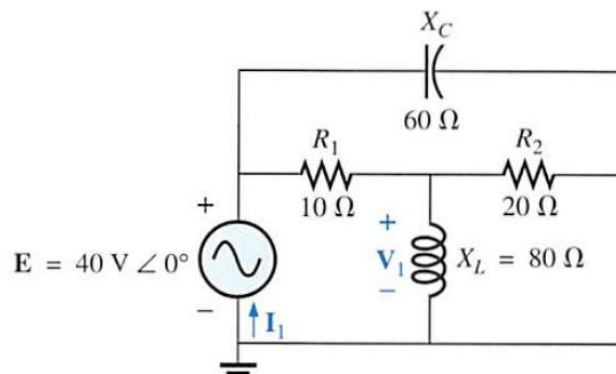


FIG. 16.42

Question 5 (16-2-10)

- \*10. For the network of Fig. 16.45:
- Find the total impedance  $Z_T$  and the admittance  $Y_T$ .
  - Find the source current  $I_s$  in phasor form.
  - Find the currents  $I_1$  and  $I_2$  in phasor form.
  - Find the voltages  $V_1$  and  $V_{ab}$  in phasor form.
  - Find the average power delivered to the network.
  - Find the power factor of the network, and indicate whether it is leading or lagging.

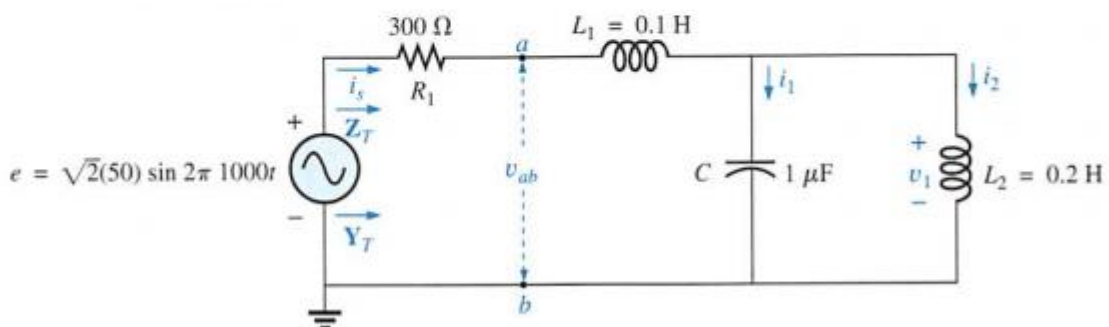


FIG. 16.45

SOLUTION

Q1

c.  $L_T = 0.26 \text{ H} = 260 \times 10^{-3} \text{ H} = 260 \text{ mH}$   
 $X_L = \omega L = 2\pi fL = 2\pi(10^3 \text{ Hz})(260 \times 10^{-3} \text{ H}) = 1632.8 \ \Omega$   
 $X_C = \frac{1}{2\pi fC} = \frac{1}{2\pi(10^3 \text{ Hz})(10 \times 10^{-6} \text{ F})} = 15.92 \ \Omega$   
 $Z_T = 47 \ \Omega + j1632.8 \ \Omega - j15.92 \ \Omega$   
 $= 47 \ \Omega + j1616.88 \ \Omega = 1617.56 \ \Omega \ \angle 88.33^\circ$

Q2

17. a.  $X_L = \omega L = (377 \text{ rad/s})(0.4 \text{ H}) = 150.8 \ \Omega$   
 $X_C = \frac{1}{\omega C} = \frac{1}{(377 \text{ rad/s})(4 \ \mu\text{F})} = 663 \ \Omega$   
 $Z_T = 30 \ \Omega + j150.8 \ \Omega - j663 \ \Omega = 30 \ \Omega - j512.2 \ \Omega = 513.08 \ \Omega \ \angle -86.65^\circ$   
 $I = \frac{E}{Z_T} = \frac{20 \text{ V} \ \angle 40^\circ}{513.08 \ \Omega \ \angle -86.65^\circ} = 39 \text{ mA} \ \angle 126.65^\circ$   
 $V_R = (I \ \angle \theta)(R \ \angle 0^\circ) = (39 \text{ mA} \ \angle 126.65^\circ)(30 \ \Omega \ \angle 0^\circ) = 1.17 \text{ V} \ \angle 126.65^\circ$   
 $V_C = (39 \text{ mA} \ \angle 126.65^\circ)(0.663 \text{ k}\Omega \ \angle -90^\circ) = 25.86 \text{ V} \ \angle 36.65^\circ$

b.  $\cos \theta_T = \frac{R}{Z_T} = \frac{30 \ \Omega}{513.08 \ \Omega} = 0.058 \text{ leading}$

c.  $P = I^2 R = (39 \text{ mA})^2 30 \ \Omega = 45.63 \text{ mW}$

f.  $V_R = \frac{(30 \ \Omega \ \angle 0^\circ)(20 \text{ V} \ \angle 40^\circ)}{Z_T} = \frac{600 \text{ V} \ \angle 40^\circ}{513.08 \ \angle -86.65^\circ} = 1.17 \text{ V} \ \angle 126.65^\circ$   
 $V_C = \frac{(0.663 \text{ k}\Omega \ \angle -90^\circ)(20 \text{ V} \ \angle 40^\circ)}{513.08 \ \Omega \ \angle -86.65^\circ} = 25.84 \text{ V} \ \angle 36.65^\circ$

g.  $Z_T = 30 \ \Omega - j512.2 \ \Omega = R - jX_C$

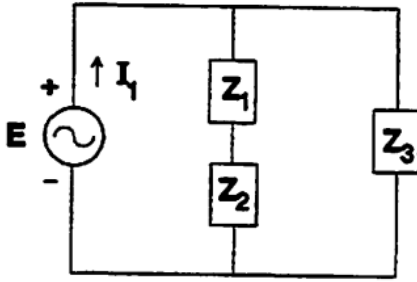
Q3

25. a.  $Z_T = 3 \ \Omega + j8 \ \Omega = 8.544 \ \Omega \ \angle 69.44^\circ$ ,  $Y_T = 0.117 \text{ S} \ \angle -69.44^\circ$   
 $Y_T = 41.1 \text{ mS} - j109.5 \text{ mS} = G - jB_L$

b.  $Z_T = 40 \ \Omega + 20 \ \Omega - j70 \ \Omega = 60 \ \Omega - j70 \ \Omega = 92.195 \ \Omega \ \angle -49.40^\circ$   
 $Y_T = 10.9 \text{ mS} \ \angle 49.40^\circ = 7.1 \text{ mS} + j8.3 \text{ mS} = G + jB_C$

c.  $Z_T = 200 \ \Omega + j500 \ \Omega - j600 \ \Omega = 200 \ \Omega - j100 \ \Omega = 223.61 \ \Omega \ \angle -26.57^\circ$   
 $Y_T = 4.47 \text{ mS} \ \angle 26.57^\circ = 4 \text{ mS} + j2 \text{ mS} = G + jB_C$

7. a.



$$\begin{aligned} Z_1 &= 10 \Omega \angle 0^\circ \\ Z_2 &= 80 \Omega \angle 90^\circ \parallel 20 \Omega \angle 0^\circ \\ &= \frac{1600 \Omega \angle 90^\circ}{20 + j80} = \frac{1600 \Omega \angle 90^\circ}{82.462 \angle 75.964^\circ} \\ &= 19.403 \Omega \angle 14.036^\circ \\ Z_3 &= 60 \Omega \angle -90^\circ \end{aligned}$$

$$\begin{aligned} Z_T &= (Z_1 + Z_2) \parallel Z_3 \\ &= (10 \Omega + 18.824 \Omega + j4.706 \Omega) \parallel 60 \Omega \angle -90^\circ \\ &= 29.206 \Omega \angle 9.273^\circ \parallel 60 \Omega \angle -90^\circ = \frac{1752.36 \Omega \angle -80.727^\circ}{28.824 + j4.706 - j60} \\ &= \frac{1752.36 \Omega \angle -80.727^\circ}{62.356 \angle -62.468^\circ} = 28.103 \Omega \angle -18.259^\circ \end{aligned}$$

$$I_1 = \frac{E}{Z_T} = \frac{40 \text{ V} \angle 0^\circ}{28.103 \Omega \angle -18.259^\circ} = 1.423 \text{ A} \angle 18.259^\circ$$

$$\begin{aligned} \text{b. } V_1 &= \frac{Z_2 E}{Z_2 + Z_1} = \frac{(19.403 \Omega \angle 14.036^\circ)(40 \text{ V} \angle 0^\circ)}{29.206 \Omega \angle 9.273^\circ} = \frac{776.12 \text{ V} \angle 14.036^\circ}{29.206 \angle 9.273^\circ} \\ &= 26.574 \text{ V} \angle 4.763^\circ \end{aligned}$$

$$\begin{aligned} \text{c. } P &= EI \cos \theta = (40 \text{ V})(1.423 \text{ A}) \cos 18.259^\circ \\ &= 54.074 \text{ W} \end{aligned}$$

10. a.

$$X_{L_1} = \omega L_1 = 2\pi(10^3 \text{ Hz})(0.1 \text{ H}) = 628 \Omega$$

$$X_{L_2} = \omega L_2 = 2\pi(10^3 \text{ Hz})(0.2 \text{ H}) = 1.256 \text{ k}\Omega$$

$$X_C = \frac{1}{\omega C} = \frac{1}{2\pi(10^3 \text{ Hz})(1 \mu\text{F})} = 0.159 \text{ k}\Omega$$

$$\begin{aligned} Z_T &= R \angle 0^\circ + X_{L_1} \angle 90^\circ + X_C \angle -90^\circ \parallel X_{L_2} \angle 90^\circ \\ &= 300 \Omega + j628 \Omega + 0.159 \text{ k}\Omega \angle -90^\circ \parallel 1.256 \text{ k}\Omega \angle 90^\circ \\ &= 300 \Omega + j628 \Omega - j182 \Omega \\ &= 300 \Omega + j446 \Omega = 537.51 \Omega \angle 56.07^\circ \end{aligned}$$

$$Y_T = \frac{1}{Z_T} = \frac{1}{537.51 \Omega \angle 56.07^\circ} = 1.86 \text{ mS} \angle -56.07^\circ$$

$$\text{b. } I_s = \frac{E}{Z_T} = \frac{50 \text{ V} \angle 0^\circ}{537.51 \Omega \angle 56.07^\circ} = 93 \text{ mA} \angle -56.07^\circ$$

c. (CDR):

$$I_1 = \frac{Z_{L_2} I_s}{Z_{L_2} + Z_C} = \frac{(1.256 \text{ k}\Omega \angle 90^\circ)(93 \text{ mA} \angle -56.07^\circ)}{+j1.256 \text{ k}\Omega - j0.159 \text{ k}\Omega}$$

$$= \frac{116.81 \text{ mA} \angle 33.93^\circ}{1.097 \angle 90^\circ} = 106.48 \text{ mA} \angle -56.07^\circ$$

$$I_2 = \frac{Z_C I_s}{Z_{L_2} + Z_C} = \frac{(0.159 \text{ k}\Omega \angle -90^\circ)(93 \text{ mA} \angle -56.07^\circ)}{1.097 \text{ k}\Omega \angle 90^\circ}$$

$$= \frac{14.79 \text{ mA} \angle -146.07^\circ}{1.097 \angle 90^\circ} = 13.48 \text{ mA} \angle -236.07^\circ$$

$$= 13.48 \text{ mA} \angle 123.93^\circ$$

d.

$$V_1 = (I_2 \angle \theta)(X_{L_2} \angle 90^\circ) = (13.48 \text{ mA} \angle 123.92^\circ)(1.256 \text{ k}\Omega \angle 90^\circ)$$

$$= 16.931 \text{ V} \angle 213.93^\circ$$

$$V_{ab} = E - (I_s \angle \theta)(R \angle 0^\circ) = 50 \text{ V} \angle 0^\circ - (93 \text{ mA} \angle -56.07^\circ)(300 \Omega \angle 0^\circ)$$

$$= 50 \text{ V} - 27.9 \text{ V} \angle -56.07^\circ$$

$$= 50 \text{ V} - (15.573 \text{ V} - j23.149 \text{ V})$$

$$= 34.43 \text{ V} + j23.149 \text{ V} = 41.49 \text{ V} \angle 33.92^\circ$$

e.  $P = I_s^2 R = (93 \text{ mA})^2 300 \Omega = 2.595 \text{ W}$

f.  $F_p = \frac{R}{Z_T} = \frac{300 \Omega}{537.51 \Omega} = 0.558 \text{ (lagging)}$